

# Bunch Shape Measurement in the Fermilab Linac

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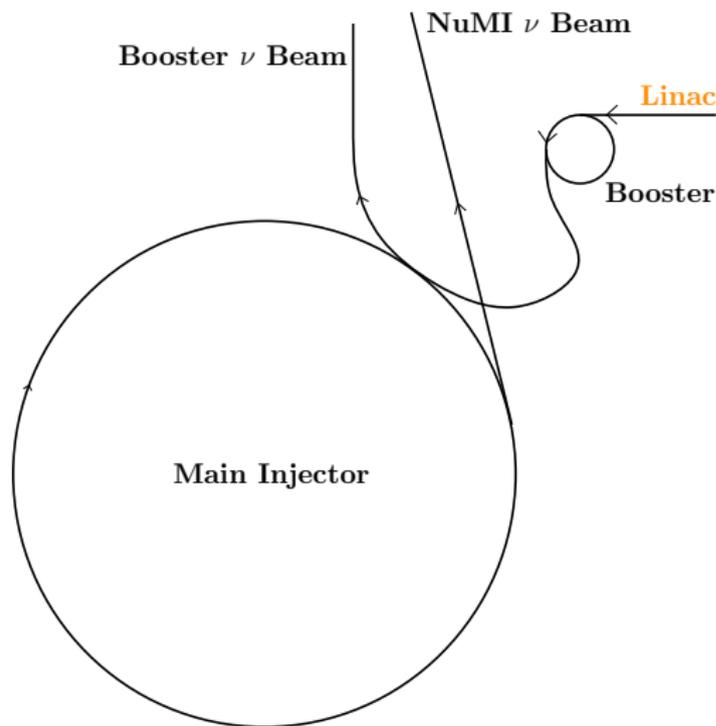


August 7, 2013

# Outline

- **The Fermilab Accelerator Complex**
  - The Fermilab Linear Accelerator
- **Introduction to Bunch Shape Monitors (BSM)**
- **The Fermilab Bunch Shape Monitors**
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  - Controlling the BSM
  - Data Acquisition
- **Testing and Calibrating Hardware Devices**
  - Testing Stepper Motors
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  - Calibrating the Focussing Lens Plates
- **BSM R&D**
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# Fermilab Accelerator Complex



A simple model of the Fermilab Accelerator Complex for the current run. Energies:

- Linac: 400 MeV
- Booster: 8 GeV
- Main Injector: 120 GeV
- *Tevatron (RIP)*:  
 $\sqrt{s} = 1.96 \text{ TeV}$

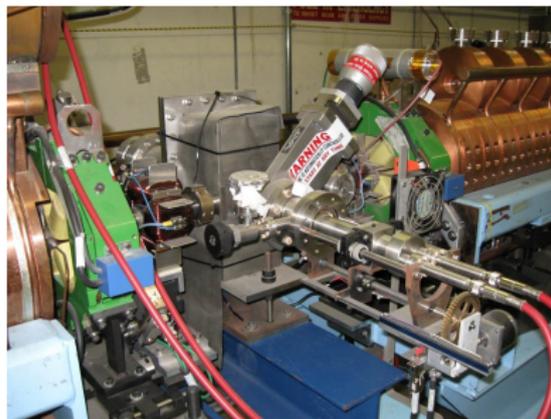
# The Fermilab Linac



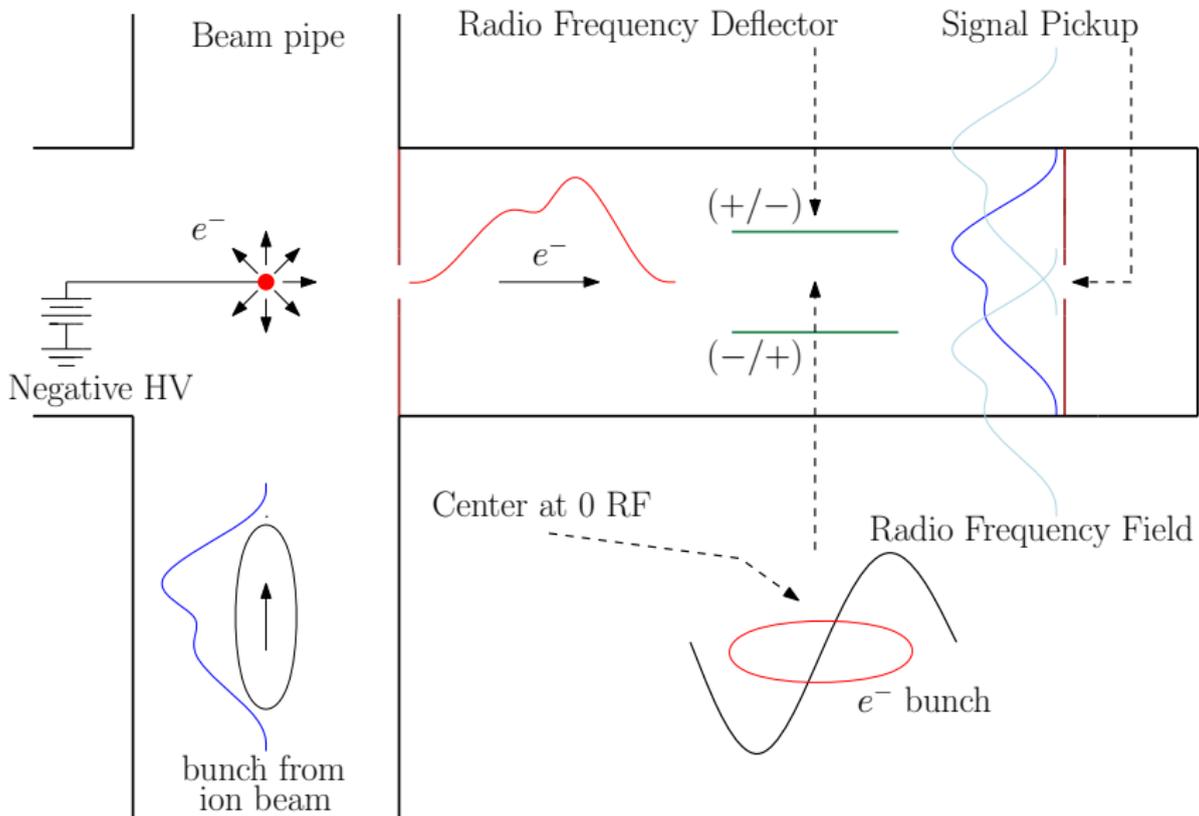
- The Linac has two main sections.
- First section: Drift tube linac operating at a bunching frequency of 201.25 MHz. Accelerates  $H^-$  beam to 116 MeV.
- Second section: Side-couple cavity linac operating at 805 MHz bunching frequency. Accelerates beam to 400 MeV.
- The BSM is installed in the transition area (between the two main sections) where the bunching frequency is 805 MHz.

# Intro to Bunch Length Detection

- Method developed in the late '80s at INR in Russia.
- BSM built at Fermilab in early '90s.
- Place thin filament at -HV in beam; secondary electrons ejected from the wire with same time structure as the beam.
- $e^-$  propagate through slit and into radio frequency cavity.
- $e^-$  structure in time transformed to a spacial structure.
- $e^-$  impinge on an electron multiplier tube (EMT).
- RF cavity phase shift to sample entire beam structure.



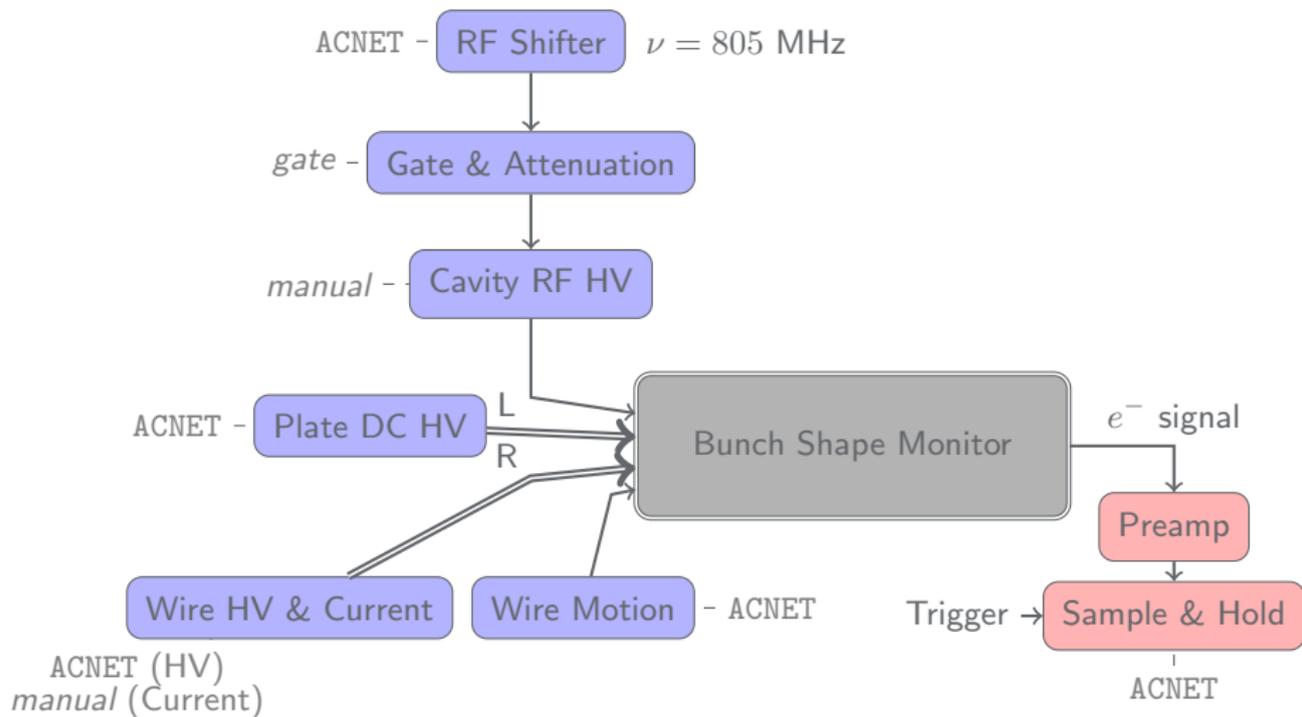
# BSM Diagram





# Controlling the BSM

A simple block/flow diagram for the Linac BSM system:

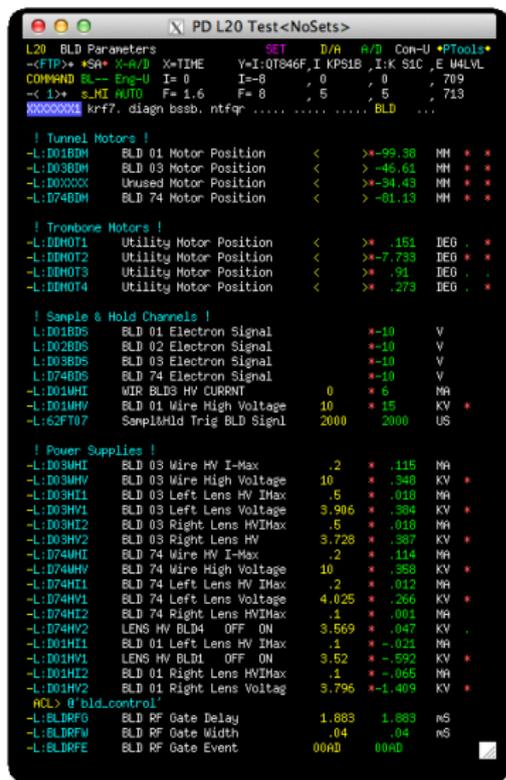


# Controlling the BSM, DAQ: ACNET, ACL

We use ACNET and ACL for setting and reading back BSM parameters.

ACL scripting language used for DAQ

- Set RF phase limit
- Set Starting RF starting phase
- Step RF phase
- Wait for a Linac pulse
- Readback phase value and EMT signal (10x)
- Step RF phase ...



```
PD L20 Test<NoSets>
L20 BLD Parameters          SET  D/A  A/D  Con-U  PTools
<-FTP>+ *SA+ X=A/B  X=TIME  Y=1:0T846F_I KPS1B_I_K SIC  E_M4LV
CDMMHD BL-- Eng-U  I=0  I=-8  0  0  709
<-K>+ s_M1 AUTO  Fa 1.6  Fa=8  5  5  713
00000001 krf7. diagn bsb. ntfr ..... BLD ...

! Tunnel Motors !
-L:D018DM  BLD 01 Motor Position < >+99.39 MM * *
-L:D038DM  BLD 03 Motor Position < >-46.61 MM * *
-L:D052DM  Unused Motor Position < >+34.43 MM * *
-L:D748DM  BLD 74 Motor Position < >-81.13 MM * *

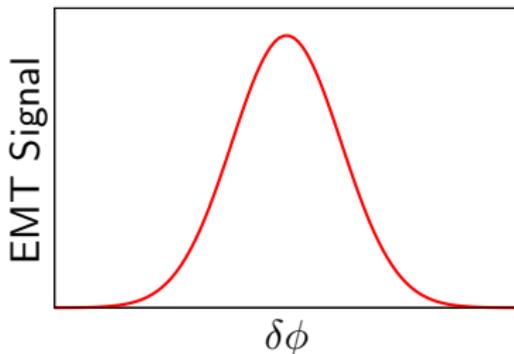
! Tronbone Motors !
-L:DDM0T1  Utility Motor Position < >+ .161 DEG * *
-L:DDM0T2  Utility Motor Position < >+7.733 DEG * *
-L:DDM0T3  Utility Motor Position < >+ .91 DEG * *
-L:DDM0T4  Utility Motor Position < >+ .273 DEG * *

! Sample & Hold Channels !
-L:D018DS  BLD 01 Electron Signal +10 V
-L:D028DS  BLD 02 Electron Signal +10 V
-L:D038DS  BLD 03 Electron Signal +10 V
-L:D748DS  BLD 74 Electron Signal +10 V
-L:D01WHI  WIP BLD3 HV CURRNT 0 * 6 MA
-L:D01WHV  BLD 01 Wire High Voltage 10 * 15 KV *
-L:62FT07  SmpHld Trig BLD Signl 2000 2000 US

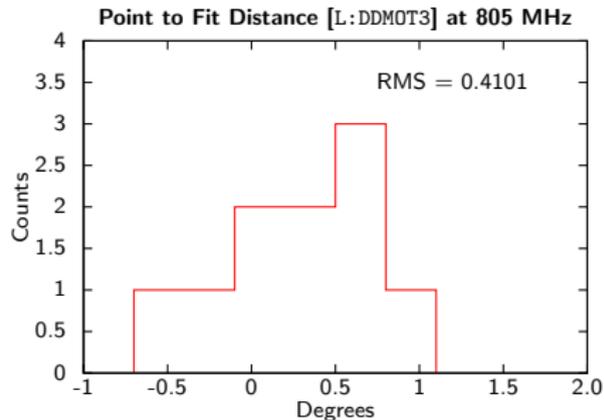
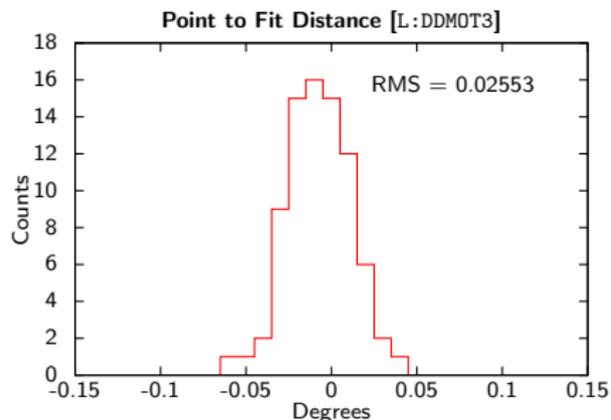
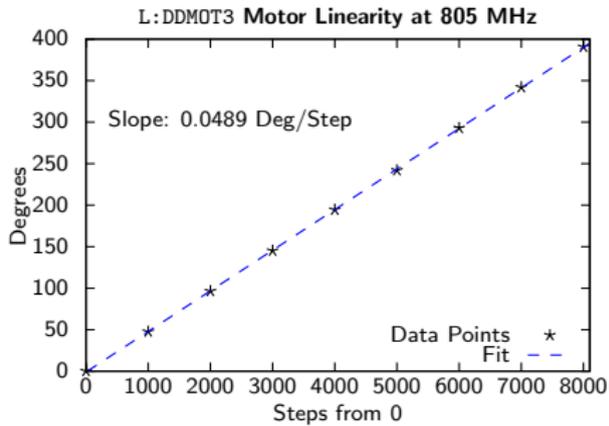
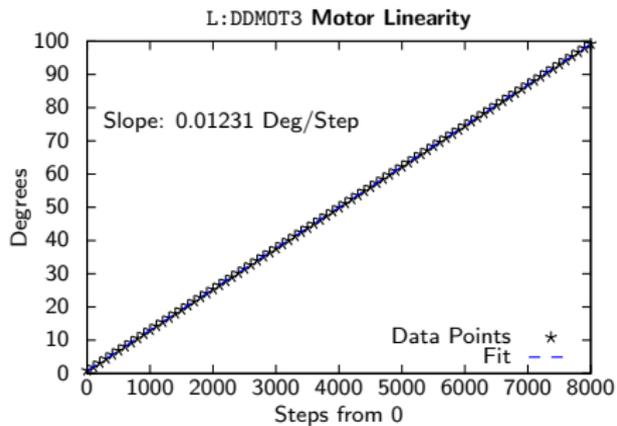
! Power Supplies !
-L:D03MH1  BLD 03 Wire HV I-Max .2 * .116 MA
-L:D03MHV  BLD 03 Wire High Voltage 10 * .348 KV *
-L:D03HL1  BLD 03 Left Lens HV IMax .5 * .018 MA
-L:D03HLV  BLD 03 Left Lens Voltage 3.906 * .384 KV *
-L:D03HI2  BLD 03 Right Lens HVIMax .5 * .018 MA
-L:D03HV2  BLD 03 Right Lens HV 3.728 * .387 KV *
-L:D74WHI  BLD 74 Wire HV I-Max .2 * .114 MA
-L:D74WHV  BLD 74 Wire High Voltage 10 * .368 KV *
-L:D74HL1  BLD 74 Left Lens HV IMax .2 * .012 MA
-L:D74HLV  BLD 74 Left Lens Voltage 4.025 * .266 KV *
-L:D74HI2  BLD 74 Right Lens HVIMax .1 * .001 MA
-L:D74HV2  LENS HV BLD4 OFF ON 3.569 * .047 KV *
-L:D01HI1  BLD 01 Left Lens HV IMax .1 * -.021 MA
-L:D01HV1  LENS HV BLD1 OFF ON 3.52 * -.692 KV *
-L:D01HI2  BLD 01 Right Lens HVIMax .1 * -.066 MA
-L:D01HV2  BLD 01 Right Lens Voltage 3.796 * -1.409 KV *
ACL> 8 bld_control
-L:BLDRFG  BLD RF Gate Delay 1.883 1.883 uS
-L:BLDRFV  BLD RF Gate Width .04 .04 uS
-L:BLDRFE  BLD RF Gate Event 00AD 00AD
```

## How the Shape is Determined

- Each Linac pulse (15 Hz) gives signal to the EMT. Many pulses contribute to one measurement
- As the phase is shifted, different segments of the spatial profile propagate through the second slit
- The measurement is then a function of the shift in phase.
- A theoretical bunch shape measurement, as a function of phase difference  $\delta\phi$ ; real measurements would not be as perfectly Gaussian.

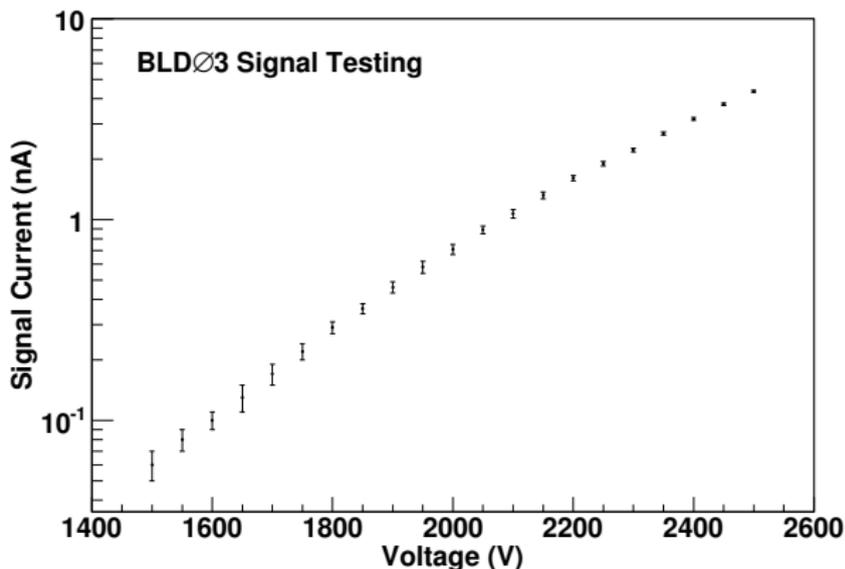


# Stepper Motor Testing



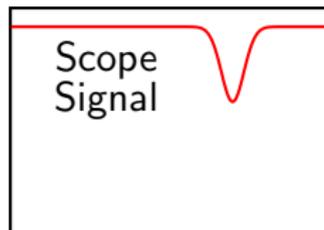
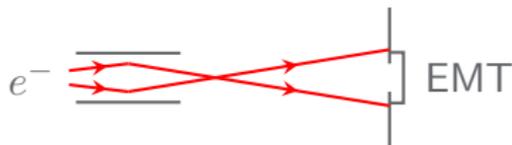
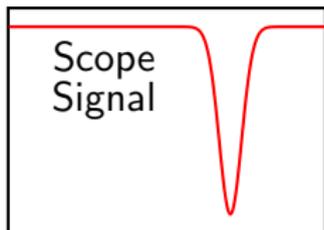
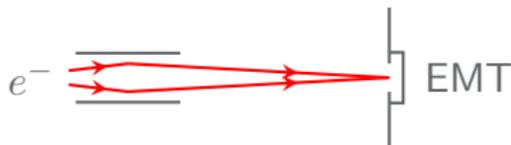
# Successful Signal

Very recently we have been able to generate a successful signal of electrons from the filament on the EMT. Applying approximately 1 A to the filament:



# Calibrating the Focussing Plates

The tungsten wire can emit electrons when not impinged on by beam by applying a current to the wire; we can calibrate how to apply voltage to the lenses in the RF Cavity without beam running.

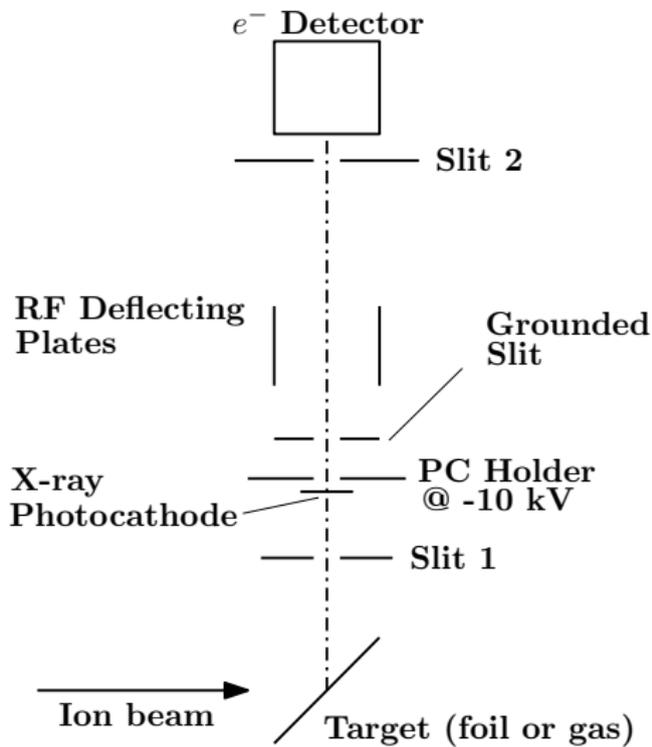


● Good focussing  $\Rightarrow$  Good signal

● Over focussed  $\Rightarrow$  Bad signal

# X-ray based BSM

- X-ray based BSM has been commissioned at ANL by Peter Ostroumov.
- Place foil in the beam line (or gas) as target. Beam-Target collisions create inner shell vacancies in target atoms. Allows for emission of X-ray photons.
- Photocathode converts X-rays into low energy electrons.
- Like the secondary electron based BSM, the X-rays and electrons in the X-ray version have the same time structure as the bunched ion beam.
- Better time resolution (10 ps vs. 5 ps) & no effect from 2  $e^-$  from the  $H^-$  beam.



# Summary and Conclusions

- Secondary electron based BSM has existed at Fermilab since the 400 MeV upgrade.
- Recommissioning of this detector has begun this summer and will continue.
  - Components of the Fermilab BSM have been tested and more will be tested
  - New data acquisition method has been developed.
  - Unfortunately, we were not able to access the Linac to diagnose problems until very recently – *but* we have been able to diagnose some problems outside of the tunnel, and we have now identified some issues in the tunnel.
- An X-ray based BSM has been commissioned at ANL and Fermilab will begin R&D on an X-ray based BSM for the PXIE effort.
- After successful measurements with the current BSM, it will be removed to install the X-ray based BSM into the Linac to prepare for one in PXIE.

# Acknowledgements

This work would not have been possible without the efforts of the internship coordinators Erik Ramberg, Roger Dixon, and Carol Angarola. Many thanks are owed to my mentor, Victor Scarpine, for his constant help throughout the summer. Invaluable aid from Elliott McCrory, Brian Fellenz, Brian Hendricks, and Kyle Hazelwood supported this project. This is supported in part by the U.S. Department of Energy, Office of Science, Office of Workforce Development for Teachers and Students (WDTS) under the Science Undergraduate Laboratory Internship (SULI) program



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# Backup

## Previous BSM Measurements

The original developer of the Fermilab BSM, Elliott McCrory, has made measurements in the past.

